

APPLYING SUB-POPULATION MEMETIC ALGORITHM FOR MULTI-OBJECTIVE SCHEDULING PROBLEMS

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Abstract: Memetic Algorithm is a population-based approach for heuristic search in optimization problems. It has shown that this mechanic performs better than traditional Genetic Algorithms for some problem. In order to apply in the multi-objective problem, the basic local search heuristics are combined with crossover operator in the sub-population in this research. This approach proposed is named as Sub-population with Memetic Algorithm, which is applied to deal with multi-objective Flowshop Scheduling Problems. Besides, the Artificial Chromosome with probability matrix will be introduced when the algorithm evolves to certain iteration for injecting to individual to search better combination of chromosomes, this mechanism will make faster convergent time for evolving. Compares with other three algorithms which are MGISPGA, NSGA-II and SPEA2, the experiments result show that this algorithm possess fast convergence and average scatter of Pareto solutions simultaneously for solving multi-objective Flowshop Scheduling Problems in test instances.

1 INTRODUCTION

In the operations research literature, Flowshop scheduling is one of the most well-known problems in the area of scheduling. Flowshops are useful tools in modeling manufacturing processes. A permutation Flowshop is a job processing facility which consists of several machines and jobs to be processed on the machines. In a permutation Flowshop all jobs follow the same machine or processing order and job processing is not interrupted once started. Our objective is to find a sequence for the jobs so that the makespan or the completion time is a minimum.

In this research, we take a close look at the evolutionary process for a permutation Flowshop

scheduling problems and come out with the new idea of generating artificial chromosomes to further improve the solution quality of the genetic algorithm. To generate artificial chromosomes, it depends on the probability of each job at a certain position. The idea is originated from Chang et al.(2005) which propose a methodology to improve Genetic Algorithms (GAs) by mining gene structures within a set of elite chromosomes generated in previous generations. Instead of replacing the crossover operator and mutation operator due to efficiency concern, the proposed algorithm is embedded into simple GA (SGA) and non-dominated sorting genetic algorithm-II (NSGA-II). The probability model acquired from the elite chromosomes will be integrated with the genetic

operators in generating artificial chromosomes, i.e., off-springs which can be applied to enhance the efficiency of the proposed algorithm. Apart from our previous researches, Harik (1999), Rastegar (2006), Zhang (2005) have discussed and proved the genetic algorithm which is based on the probability models. For a complete review of the relative algorithms discussed above, please refer to Larranaga (2001), Lozano (2006), and Pelikan (2002). In most recent works of evolutionary algorithm with probability models, they all concentrate on solving continue problems rather than discrete problems. There are only few researches in applying evolutionary algorithm with probability models to resolve discrete problems.

2 METHODOLOGY

A new approach is developed in this research which is called SPMA. The method is proposed to solve Flowshop scheduling problems and will be compared with SPGA, NSGA-II and SPEA-II. Through literature reviews, we find that SPGA has very good diffusivity when solving multi-objective problems; however, as for convergence, there still remains room for improvement. Thus, the research tries to strengthen the solution convergence of SPGA by mining gene structures and local search heuristic. Except for the original mining gene structures (Chang 2005), we called Artificial chromosomes (AC).

2.1 Generating Artificial Chromosomes

During the evolving process of the GA, all the chromosomes will converge slowly into certain distribution after the final runs. If we take a close look at the distribution of each gene in each assigned position, we will find out that most the genes will be converged into certain locations which means the gene can be allocated to the position if there is a probabilistic matrix to guide the assignment of each gene to each position. Artificial Chromosomes (AC) are developed according to this observation and a dominance matrix will record this gene distribution information. The dominance matrix is transformed into a probability matrix to decide the next assignment of a gene to a position. Consequently, AC is integrated into the procedure of genetic algorithm and it attends to improve the performance of genetic algorithm. The primary procedure is to collect gene information first and to use the gene information to generate artificial chromosomes.

Before collecting the gene information, AC collects the chromosomes whose fitness is better by comparing the fitness value of each chromosome with average fitness value of current population. Then artificial chromosome is embedded into the genetic algorithm. The detailed steps are described in the following:

1. To convert gene information into dominance matrix:

Before we collect gene information, selection procedure is performed to select a set of chromosomes. Then, for a selected chromosome, if job i exists at position j , the frequency is added by 1. To demonstrate the working theory of the artificial chromosome generation procedure, a 5-job problem is illustrated. Suppose there are ten sequences (chromosomes) whose fitness is better than average fitness. Then, we accumulate the gene information from these ten chromosomes to form a dominance matrix. As shown in the left-hand side of Figure 1, there are two job 1, two job 2, 2 two 3, one job 4, and three job 5 on position 1. Again, there are 3 job 1, 1 job2, 2 job3, 3 job4, and 1 job5 on position 2. The procedure will repeat for the rest of the position. Finally, the dominance matrix contains the gene information from better chromosomes is illustrated in the right-hand side of Figure 1.

2. Generate artificial chromosomes:

As soon as we collect gene information into dominance matrix, we are going to assign jobs onto the positions of each artificial chromosome. The assignment sequence for every position is assigned randomly, which is able to diversify the artificial chromosomes. After we determine the assignment sequence, we select one job assigned to each position by roulette wheel selection method based on the probability of each job on this position. After we assign one job to a position, the job and position in the dominance matrix are removed. Then, the procedure continues to select the next job until all jobs are assigned. Assume the first job is to be assigned at position 3 in the beginning. The frequency of each job at position 3 is [1, 3, 1, 1, and 4] starting from job 1 to job 5. Because the number of total frequency is 10, the corresponding probability for job 1 is 1/10; job 2 is 3/10, and so on. Then, we accumulate the probability from job 1 to 5 and roulette wheel select is able to apply this accumulated probability. If a random probability 0.6 is generated, then job 4 is assigned to position 3.

3. Replacement strategy:

After embedding artificial chromosomes into the population, we use $1 + k$ strategy, which combines previous parent population and artificial chromosomes. Then, we select better 1 chromosomes from the combined population. Consequently, better solutions are preserved to the next generation.

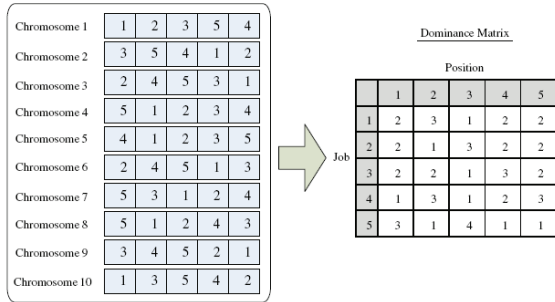


Figure 1: To collect gene information and converted into a dominance matrix.

During the assignment of each job to a specific position, the dominance matrix will be updated continuously. For example, after assigning job 4 at position 3 and suppose position 2 is the next one to be assigned. An updated dominance matrix is shown in Figure 2.

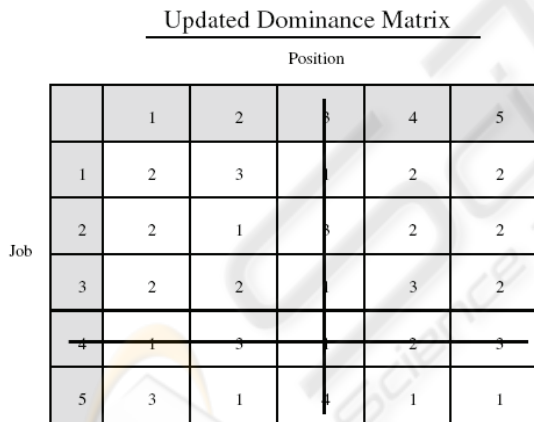


Figure 2: The updated dominance matrix after assigning job 4 at position 3.

Next, the probability of each job is recalculated as well as the accumulated probability. Then, a roulette wheel selection method will select a job based on the probability of each job. Consequently, the algorithm iteratively assigns jobs to vacant positions until all jobs are assigned.

2.2 The procedure of SPMA

The detailed procedure of SPMA is shown as the

following:

(N_s is the number of sub-populations; g is the number of generations; k is the interval number of artificial chromosomes' generations.)

```

1. Initialize();
2. DividePopulation();
3. AssignWeightToEachSubGroup();
4. for i=1 to Iterations
5.     for j=1 to Groups
6.         if i % k == 0
7.             ArtificialChromosome(j);
8.         <GenerateArtificialChromosome(j);
9.             LocalSearch(j);
10.            SurvivalOfThefittest(j);>
11.        else
12.            GeneAlgorithm(j);
13.        <Selection(j);
14.            Crossover(j);
15.            Mutation(j);
16.            LocalSearch(j);
17.            SurvivalOfThefittest(j);>
18. FindPareto(Groups);
19. UpdatePareto(Groups);
    
```

Compared with SPGA, this approach is different in that it has the mechanism of creating AC, local search heuristic and the sorting information of chromosomes in each mutation is recorded for the use of creating AC and placing them in the mating pool for evolution. In the end, $D1_R$ is a metric which considers the convergence and diversity simultaneously (Knowles, 2002) and it is adopted in this research to evaluate the solution quality. Its main concept is to calculate the shortest distance between each solution in the Pareto-Solution set and the set to be compared with, and then calculate the mean value. The smaller $D1_R$ is the better.

3 EXPERIMENTAL TESTS

The research uses the Flowshop scheduling case study by Ishibuchi (2003) in which four types were included in the bi-objective flow-shop problems; they were 20 jobs in 20 machines, 40 jobs in 20 machines, 60 jobs in 20 machines and 80 jobs in 20 machines. Two objectives are the total completion time (Cmax) and maximum tardiness (Tmax). The processing and completion time are the same as used in Ishibuchi et al. (2003). The experimental results will be compared with those of SPGA, NSGA-II and SPEA-II. The testing result of this sample problem is depicted in Table 1 and Figure 3. It is obvious that SPMA performs better in the small and medium size problem (job = 20, 40, 60). And it deserve to be

mentioned is the Std. of SPMA is much less than other models.

Table 1: The algorithm comparison with other methods.

Instance (job)	NSGA II		SPEA II	
	Ave.	Std.	Ave.	Std.
20	43.05	14.42	37.35	14.22
40	146.36	28.71	138.6*	19.9
60	321.12	57.86	291.02	52.78
80	424.96	93.92	394.14	63.79
Instance (job)	SPGA		SPMA	
	Ave.	Std.	Ave.	Std.
20	38.62	9.44	22.46*	8.89
40	146.21	21.09	142.40	20.03
60	341.86	94.15	261.24*	34.49
80	344.45*	99.12	515.34	75.72

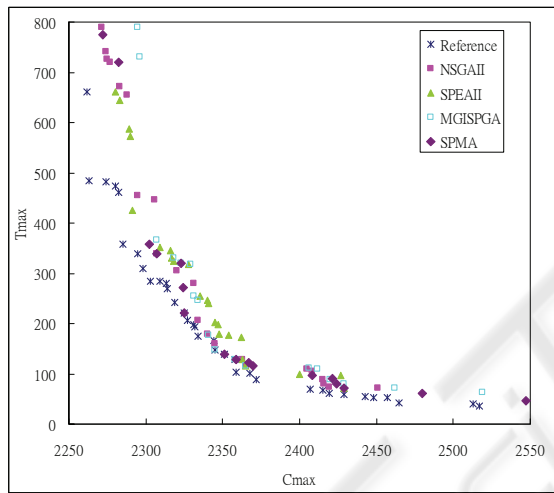


Figure 3: The plot of algorithms with reference Pareto set of SPMA.

According to the above-mentioned four testing results, we find that when solving more complex problems, it is harder to find the improving effectiveness of SPMA. Along with the increasing number of jobs, the problems become more complex and thus the improving effectiveness of SPMA can't be obviously noticed.

4 CONCLUSIONS

Through this study, we can verify that by combining AC and local search heuristic with SPGA, multi-objective scheduling problems can be solved more effectively, especially in the small and medium size problem. In the future, SPMA can be further extended to three objectives or multidimensional

continuous problems. And the procedures of SPMA might be improved to deal with large size problem.

Further investigation will be carried out to examine whether it is possible to generate elite chromosomes through better mining algorithms. It is also suggested that different objectives of Flowshop scheduling problems can be further tested such as the arrival time of job is considered, and those with more complex requirements such as sequence dependent setup times.

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