

XHITS

Multiple Roles in a Hyperlinked Structure

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Keywords: Search engines, Keyword-based ranking, Link- based ranking.

Abstract: The WWW is a huge and rich environment. Web pages can be viewed as a large community of elements that are connected through links due to several issues. The HITS approach introduces two basic concepts, hubs and authorities, that reveal some hidden semantic information from the links. In this paper, we present XHITS, a generalization of HITS, that models multiple classes problems and a machine learning algorithm to calibrate it. We split classification influence into two sources. The first one is due to link propagation, whereas the second one is due to classification reinforcement. We derive a simple linear iterative equation to compute the classification values. We also provide an influence equation that shows how the two influence sources can be combined. Two special cases are explored: symmetric reinforcement and positive reinforcement. We show that for these two special cases the iterative scheme converges. Some illustrative examples and empirical test are also provided. They indicate that XHITS is a powerful and efficient modeling approach.

1 INTRODUCTION

The link structure of the WWW provides valuable information that can be used to improve information retrieval quality (Borodin et al., 2001),(Chakrabarti et al., 2001),(Lempel and Moran, 2001),(Ding et al., 2002a). There are lot of different proposals for searching and ranking information on the WWW, (Mendelzon and Rafiei, 2000), (Cohn and Chang, 2000), (Giles et al., 2000), (yu Kao et al., 2003), (Fowler and Karadayi, 2002), (Ding et al., 2002b), (Agosti and Pretto, 2005), (Mizzaro and Robertson, 2007),(Lempel and Moran, 2001). Others just to improve the quality of existing ones, as incorporating user behavior data can significantly improve ordering of top results in real web search setting, (Agichtein et al., 2006).

In a seminal paper (Kleinberg, 1999), Jon Kleinberg introduced the notion of two fundamental categories of web pages: authorities and hubs.

Good hubs are the ones that point to good authorities, whereas good authorities are the ones that are pointed by good hubs.

This mutually reinforcing relationship can be easily formulated through a system of equations. The HITS algorithm finds a solution to this system.

Here, we generalize Kleinberg's approach by introducing new page categories. The new system of

equations can still be solved by the *power method* as in HITS.

Hence, our XHITS method allows to incorporate concepts that capture different roles of pages in the Web domain, such as: hubs, authorities, sponsors, novelty, portals, mirrors, etc, (Filho, 2005). It is up to the modeler to define the corresponding semantic of these categories through the equations that translate their mutual reinforcement.

This modeling framework provides a clean method to extract multiple concepts in a hyperlinked structure such as the Web. Actually, these concepts are extremely related with the human judgments about importance of the information on the web. Now, we have the engineering knowledge as a formal method to incorporate several different roles played by individuals in a hyperlinked environment.

To illustrate this approach, we present a simple extension to the hubs and authorities categories. This extension takes into account that good authorities sometimes also point to novelty in a subject.

Hence, whenever some strong authorities point to a given document, then this document must receive our attention, even if it is not pointed by any strong hub. Chances are that this is relevant new material that has not been widespread to the hubs. In this illustration, we also consider that good authorities can play the role of novelty finders. On the other hand, we

also introduce a naive notion of portals: good portals are pages that point to good hubs.

In section 2, we describe our modeling approach and the corresponding algorithm.

In section 3, we show a simple illustration with novelties and portals. In section 4, we introduce a machine learning procedure to calibrate the model. Next, in section 5, we examine the empirical behaviour of the proposed approach. Finally, in section 6, we draw our conclusions and final comments on our findings.

2 XHITS

Here, we first restate the HITS Algorithm in block matrix form. Next, we highlight some key properties that are explored on the proposed extension XHITS.

We introduce the notion of influence matrix, a linear structure that combines both the mutual classifications reinforcement and the link propagation mechanism. Two special cases naturally follow from this structure: symmetric reinforcement and positive reinforcement. Under some mild assumptions, we show convergence proofs for an extended iterative equation.

As usual, we represent web pages as the nodes in a directed graph. The links are represented by the edges of this graph. The corresponding adjacency matrix is denoted by A . The extraction of these graphs is made in the same way of Jon Kleinberg did in his approach, (Kleinberg, 1999).

2.1 HITS

In the HITS model, each page i has a corresponding authority weight a_i and also a hub weight h_i . These weights are subject to mutual reinforcement through the link structure.

Formally, we have

$$a \propto A^T h$$

$$h \propto A a$$

This system of two sets of linear constraints can be condensed in block matrix form, given the unique equation

$$\begin{bmatrix} a \\ h \end{bmatrix} \propto \begin{bmatrix} 0 & A^T \\ A & 0 \end{bmatrix} \cdot \begin{bmatrix} a \\ h \end{bmatrix} \quad (1)$$

Equation 1 provides immediate ways to iteratively compute both a and h . Nevertheless, it is necessary to guarantee that the values converge.

In order to examine the convergence issues involved in iteration 1, we define the *influence matrix* M by

$$M = \begin{bmatrix} 0 & A^T \\ A & 0 \end{bmatrix} \quad (2)$$

It is easy to see that M is a symmetric matrix. Therefore, iteration 1 is just an instance of the well known *Power Method* for eigenvalues extraction. Hence, the iteration converges.

Another interesting representation of M is given by

$$M = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \otimes A^T + \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \otimes A \quad (3)$$

In 3, we use the direct product \otimes to reveal the influence structure, (Searle, 1982).

2.2 The Algorithm

To enhance the basic *Hubs and Authorities Model*, we introduce new categories. Now, instead of just two concepts, we have k categories.

Hence, each page i receives its corresponding u th class weight c_{iu} , where $u = 1, \dots, k$. These weights are reinforced through the links. We have both forward and backward influences, and these are not necessarily symmetrical.

Whenever page i points to page j , each weight c_{jv} contributes to the score of c_{iu} with a linear amount of $F_{uv} \cdot c_{jv}$. Similarly, when j points to i , each weight c_{jv} contributes to the score of c_{iu} with a linear amount of $B_{uv} \cdot c_{jv}$. Therefore, we have a $k \times k$ matrix F of forward category influences, and a $k \times k$ matrix B of backward category influences.

Formally, for each weight c_{iu} we have

$$c_{iu} \propto \sum_{j \rightarrow i} \sum_{v=1}^k B_{uv} \cdot c_{jv} + \sum_{i \rightarrow j} \sum_{v=1}^k F_{uv} \cdot c_{jv}$$

By stating these equations in matrix form we get

$$C \propto A^T C B^T + A C F^T \quad (4)$$

Equation 4 provides an efficient iterative computation to find C , provided convergence is guaranteed.

2.3 Influence Structure

Equation 4 can be restated by transforming matrix C into a vector, that is, by

$$\text{vec}(C) \propto \text{vec}(A^T C B^T + A C F^T)$$

Using well known properties of the *vec* operator (Searle, 1982), we get

$$\text{vec}(C) \propto [(B \otimes A^T) + (F \otimes A)] \cdot \text{vec}(C)$$

The matrix M defined by

$$M = (B \otimes A^T) + (F \otimes A) \quad (5)$$

is called the *influence matrix*.

The influence matrix reveals the combination of the two sources of mutual influence: link propagation and category reinforcement. Therefore, it is very convenient when one investigates theoretical aspects of the model.

Next, we highlight two important special cases where we have convergence for iteration 4.

2.4 Symmetric Reinforcement

In the case of *symmetrical mutual reinforcement*, we have that

$$B_{vu} = F_{uv}$$

for all u and v . Hence, we have that $B = F^T$.

Now, equation 5 simplifies to

$$M = (F \otimes A)^T + (F \otimes A) \quad (6)$$

It is easy to see that M is a symmetric matrix.

The *Power Method* provides a straightforward algorithm to find both the largest eigenvalue and a corresponding eigenvector for M . Therefore, iteration 4 converges and generalizes Kleinberg's original proposal.

Finally, we state a Proposition that characterizes symmetric reinforcement.

Proposition. Let us assume that $A \neq A^T$. Then, the influence matrix M is symmetric iff $B = F^T$.

Proof.: The sufficiency condition was the subject of the discussion above. To prove the condition is necessary, observe that

$$M = M^T$$

implies that

$$(B \otimes A^T) + (F \otimes A) = (B \otimes A^T)^T + (F \otimes A)^T$$

that is,

$$(B - F^T) \otimes A^T = (B^T - F) \otimes A$$

From the definition of direct product, it follows that for all pair of pages r and s and for all pair of classification degrees i and j we have

$$(B_{ij} - F_{ji}) \cdot A_{rs} = (B_{ji} - F_{ij}) \cdot A_{sr}$$

By assumption, we have a particular r and s such that $A_{rs} = 1$ and $A_{sr} = 0$. Hence, we obtain that,

$$(B_{ij} - F_{ji}) \cdot 1 = (B_{ji} - F_{ij}) \cdot 0$$

Therefore, $B_{ij} = F_{ji}$ for all pairs of classification degrees i and j . This completes our proof.

2.5 Positive Reinforcement

Another interesting case of the XHITS multiple roles model is when we have that all B_{uv} and F_{uv} are positive. This is called *positive reinforcement*.

Under this assumption, it is easy to see that the influence matrix M is also positive.

In this case, the *Perron-Frobenius Theorem* asserts that the largest eigenvalue is positive and there is also a corresponding eigenvector with positive coordinates. This is enough to guarantee convergence of iteration 4.

3 NOVELTIES AND PORTALS

To illustrate the XHITS approach, we extend the basic *Hubs and Authorities Model*, by introducing two new concepts: novelties and portals.

Now, each page i receives its corresponding novelty weight n_i and portal weight p_i . We extend the conversation by introducing novelty and portal weights into our constraints. First, observe that good authorities are always pointed by good hubs, sometimes pointed by good portals and also point to good novelties. Hence, we have that

$$a_i \propto \sum_{j \rightarrow i} h_j + w_1 \cdot \sum_{j \rightarrow i} p_j + w_2 \cdot \sum_{i \rightarrow j} n_j \quad i = 1, \dots, n$$

By a similar reasoning, we obtain the equations for the other three weights. By stating these equations in matrix form we get

$$a \propto A^T h + w_1 A^T p + w_2 A n$$

$$h \propto A a + w_3 A^T p + w_4 A n$$

$$p \propto w_1 A a + w_3 A h + w_5 A n$$

$$n \propto w_2 A^T a + w_4 A^T h + w_5 A^T p$$

where w_1, w_2, w_3, w_4 and w_5 are additional effect reduction parameters.

One can combine the four equations above into a single one, to obtain

$$\begin{bmatrix} a \\ h \\ p \\ n \end{bmatrix} \propto \begin{bmatrix} 0 & A^T & w_1 A^T & w_2 A \\ A & 0 & w_3 A^T & w_4 A \\ w_1 A & w_3 A & 0 & w_5 A \\ w_2 A^T & w_4 A^T & w_5 A^T & 0 \end{bmatrix} \cdot \begin{bmatrix} a \\ h \\ p \\ n \end{bmatrix} \quad (7)$$

It is easy to see that in this illustration we have $B = F^T$ and

$$F = \begin{bmatrix} 0 & 0 & 0 & w_2 \\ 1 & 0 & 0 & w_4 \\ w_1 & w_2 & 0 & w_5 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Equation 7 is a special case of mutual reinforcement XHITS. Therefore, this iteration converges.

Observe that the parameters w_1, w_2, w_3, w_4 and w_5 can be used to fine tune our method.

4 MACHINE LEARNING FOR XHITS

4.1 Approach

As seen in early sections, we have a set of queries, each one having its own graph of pages. In particular case, the XHITS algorithm gives us a ranking of these pages through the eigenvector associated to the biggest eigenvalue of M:

$$M = \begin{bmatrix} 0 & A^T & w_1 A^T & w_2 A \\ A & 0 & w_3 A^T & w_4 A \\ w_1 A & w_3 A & 0 & w_5 A \\ w_2 A^T & w_4 A^T & w_5 A^T & 0 \end{bmatrix} \quad (8)$$

where w_i are parameters that you can use to fine tune the method.

Basically, as we change the values of these parameters, the value of eigenvector modifies and the rank as well. Under this assumption, we can define the XHITS as a function $H_j(\vec{w}, G_i) = O_{ij}$, where \vec{w} is the vector with the parameters w_1, w_2, \dots, w_5 , G_i is the graph related with the query q_i , O_{ij} is the rank of the page j and the query i . So we can view H_j as ranking function that gives each website a rank according to their topological organization and mutual reinforcement influence.

But we don't know what is the best value of $\vec{w} = (w_1, w_2, w_3, \dots, w_5)$. Our approach to learn these parameters will be machine learning. That means, that we simply give the information we have to a learning algorithm and it use this information to forms \vec{w} correctly. In the next section, we start with explanation about gradient descent method and how it can be applied on the problem of finding the vector \vec{w} .

4.2 Learning of Parameters with Gradient Descent

To proceed with the learning process of W, we have some input and output pairs $(X_{11}, Y_{11}), \dots, (X_{1q}, Y_{1q}), \dots, (X_{pq}, Y_{pq})$, that we will use to learn the parameters that makes $O_{ij} \approx Y_{ij}$.

When $H_j(\vec{w}, G_i)$ gets the input \vec{w} and G_i it computes a value O_{ij} , and if O_{ij} came from \vec{w} we are looking for, then O_{ij} would already be very close to Y_{ij} . Therefore we need a measure for the error between O_{ij} and Y_{ij} . This is done by the cost function C_i , which is the deviation value between the output O_{ij} of the current value of \vec{w} , and the target output Y_{ij} we want to reach with the learning machine.

The overall cost function, which summarizes all errors then would be

$$E_{train} = \frac{1}{pq} \sum_{i=1}^p \sum_{j=1}^q C_i(Y_{ij}, O_{ij}) \quad (9)$$

and replacing O_{ij} for $H_j(\vec{w}, G_i)$ in 9, we have

$$E_{train} = \frac{1}{pq} \sum_{i=1}^p \sum_{j=1}^q C_i(Y_{ij}, H_j(\vec{w}, G_i)) \quad (10)$$

As you can see, \vec{w} is a direct input to the training function and the set of pairs $(X_{11}, Y_{11}), \dots, (X_{1q}, Y_{1q}), \dots, (X_{pq}, Y_{pq})$ is definite, so we can use the gradient descent method to find a value of \vec{w} that minimizes E_{train} .

Method 1. (The gradient descent method) This is an approximation method, which at each point chooses the direction of steepest descent to find the minimum of a multidimensional function f , which is a function of the variables w_1, w_2, \dots, w_n . So, this method operates according to the following rule, when proceeding from one iterate to the next:

$$w_i^{m+1} = w_i^m - \mu \frac{\partial f(\vec{w})}{\partial w_i} \quad (11)$$

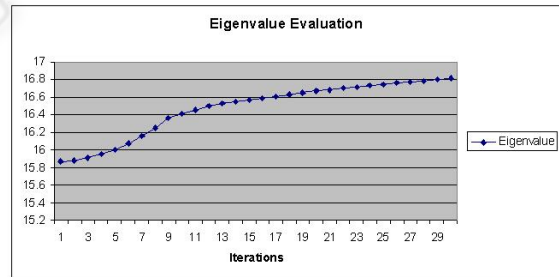


Figure 1: Evaluation of the eigenvalue during the neighborhood searching.

In the above:

- $\frac{\partial f(\vec{w})}{\partial w_i}$ denotes the partial derivative of f with respect to w_i , which is evaluated at \vec{w} ;
- μ denotes what is usually referred to as the step size.

By knowing $\frac{\partial E_{train}}{\partial \vec{w}}$, the gradient descent algorithm for this problem can be adapted to:

$$\vec{w}^{m+1} \leftarrow \vec{w}^m - \mu \frac{\partial E_{train}}{\partial \vec{w}} \quad (12)$$

Now, we have to find the partial derivatives of E_{train} with respect to the vector \vec{w} :

$$\frac{\partial E_{train}}{\partial \vec{w}} = \frac{1}{pq} \sum_{i=1}^p \sum_{j=1}^q \frac{\partial C_i}{\partial \vec{w}} (Y_{ij}, H_j(\vec{w}, G_i)) \quad (13)$$

In this way, we can define the deviation function C_i as $(Y_{ij} - O_{ij})^2$ and applying it in 13 we have:

$$\frac{\partial E_{train}}{\partial \vec{w}} = -\frac{2}{pq} \sum_{i=1}^p \sum_{j=1}^q \left[(Y_{ij} - H_j(\vec{w}, G_i)) \frac{\partial H_j(\vec{w}, G_i)}{\partial \vec{w}} \right] \quad (14)$$

But, $H_j(\vec{w}, G_i)$ gives the eigenvector associated with the biggest eigenvalue of M associated with G_i , so, the partial derivatives of $H_j(\vec{w}, G_i)$, corresponds to:

$$\frac{\partial H_j(\vec{w}, G_i)}{\partial \vec{w}} = \frac{\partial x_i}{\partial \vec{w}} \quad (15)$$

where \vec{x}_i denotes the eigenvector of M . According to (Kalaba et al., 1981), we can write the partial derivatives of \vec{x}_i as:

$$\frac{\partial x_i}{\partial \vec{w}} = \sum_{l=1}^n \left[\frac{(x_l^T \frac{\partial M}{\partial \vec{w}} x_l)}{(\lambda_i - \lambda_l)} \right] x_l \quad (16)$$

However, to calculate 16 we have to find all eigenvectors and eigenvalues of M , and it is, in computational terms, expensive. Instead of using 16, we decide to use the partial derivatives of the eigenvalue associated with \vec{x}_i , extracted from (Kalaba et al., 1981), that is:

$$\frac{\partial \lambda_i}{\partial \vec{w}} = (x_i^T \frac{\partial M}{\partial \vec{w}} x_i) \quad (17)$$

We used this adaptation because there is an inherent relation between eigenvalues and eigenvectors, and it's a good simplification without loss of generality. The graphics in figures 1 and 2 shows empirically this relation. The value of the eigenvalue is getting up while the value of E_{train} is getting down and converges to a local minimum. Next section shows a description of the algorithm for the approach discussed here.

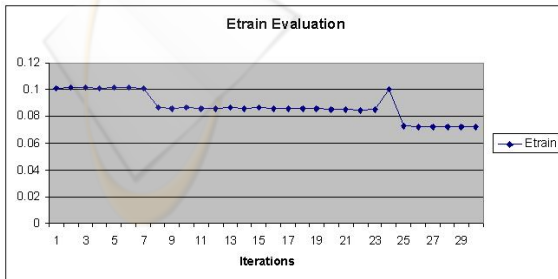


Figure 2: Evaluation of the E_{train} during the neighborhood searching.

4.3 Algorithm

We are now able to write the algorithm that teaches $H_j(\vec{w}, G_i)$. The algorithm can be resumed as shown in table 1.

Table 1: Learning Algorithm for $H_j(\vec{w}, G_i)$ function.

Step	Activity
1	Initiates \vec{w}^1 with some values.
2	Calculate the eigenvectors, x_i , and eigenvalues, λ_i for $M(\vec{w})$ for the training set
3	Calculate $\frac{\partial x_i}{\partial \vec{w}}$
4	Calculate \vec{w}_i^{m+1}
5	Calculate $E_{train} = \frac{1}{pq} \sum_{i=1}^p \sum_{j=1}^q C_i(Y_{ij}, O_{ij})$ and if it is small enough stop, else go back to step 2

5 EXPERIMENTAL RESULTS

To illustrate the computational issues and also to highlight the modeling power of XHITS, we perform some exploratory experiments.

5.1 Test Goal

Our major performance measure is *ranking quality*. As a first instance, we examine the naive Novelties and Portals classification model.

Our goal is to show that even this simple model provides a remarkable improvement over previous algorithms. It shows a ranking quality similar to the complex algorithms engineered inside commercial search engines.

5.2 Test Environment

We adopt a pragmatic scheme to build our benchmark. First, we fix a set of queries. There are 300 queries in the set with no overlaps, derived from the most google's fifteen searched topic for each week in a period of five months. Those queries have been chosen because if our approach reveals a good performance with them, it will be close from the real searched topics at least.

As well-known, cross-validation is the statistical practice of partitioning a sample of data into subsets such that the analysis is initially performed on a single subset, while the other subset(s) are retained for subsequent use in confirming and validating the initial analysis. To test the learning algorithm presented in this work, we randomly split up the benchmark set

Table 2: Precision at 10, HITS and XHITS.

Algorithm	Precision at Ten (P@10)
HITS	0.125678
XHITS	0.385678

into two subsets: one is the training set and the other is the test set. The training set is used for fine-tuning the parameters w_1, w_2, \dots, w_5 . We validated the learning process applying the 10-fold cross validation in the training set. After the training step, the parameters had chosen are used and the XHITS is applied in the test set.

Next, instead of using humans to provide the reference rank for each query, we use one *artificial expert*: Google. This Search Engine is built around several algorithms that engineer a lot of specific Web knowledge. For our purpose, we considered the fourth first pages returned by the expert as the relevant ones.

5.3 Test Results

Different performance metrics are appropriate in different circumstances. For recommendation systems and information retrieval settings, where results are displayed to users incrementally with the most relevant first, the metric P@10 is most appropriate. It represents the precision of the first page of results displayed. To evaluate ranking quality we focus on the top 10 pages ranked by the artificial expert. We considered these as the relevant pages.

Hence, we check the average precision performance of the Novelties and Portals model. We just need to count how many relevant pages were recovered among the top ranked by our model.

In table 2 we summarize the test results. One can see a 206% improvement of XHITS over HITS on the average. Comparing the proximity of the ranks produced by XHITS and Google, the maximum proximity was observed for query *daytime emmys* and the minimum for query *narnia*. The corresponding values were 1 and 0.1 in P@10. During the period we selected the queries, *Narnia*, the movie, was about to be launched and the official site was returned between the ten first pages at least. The *daytime emmys* topic is related with National Academy television that was happening in that week. All the ten first pages matched with Google's first ones. You can see the result in table 3.

Table 3: The first ten links returned by XHITS engine after the training.

Position	URL
1	http://www.emmyonline.org/emmy/daytime.html/
2	http://www.emmys.tv/awards/daytimeawards.php/
3	http://www.emmyonline.org/
4	http://en.wikipedia.org/wiki/Daytime_Emma_Award/
5	http://www.soapcentral.com/soapcentral/awards/emmys/index.php/
6	http://www.tvweek.com/news/2008/06/tyra_ellen_light_winners_at_da.php/
7	http://www.miamiherald.com/776/story/576599.html/
8	http://www.msnbc.msn.com/id/25291338/
9	http://www.infoplease.com/ipa/A0151371.html/
10	http://television.aol.com/daytime-emmys/

6 CONCLUSIONS AND FUTURE WORK

Searching the web accurately is becoming increasingly critical as the web grows. In this paper we explored the utility of extending the HITS model to improve web search ranking. The XHITS model provides a powerful approach to engineer key Web characteristics into ranking algorithms. But we had to deal with new parameters that didn't exist in the Kleinberg's approach.

So, an interesting open problem is how to find the set of parameters that best fits to a given data set. This is a learning problem that we are currently working on and trying to evaluate. Furthermore, by using machine learning was easy to find parameter values that give to simple XHITS models the same precision power of deep Web knowledge specific algorithms. This approach has its own benefits, as follow:

- Since the parameters learned consist of several different queries put together it is harder to manipulate results;
- Given that the advances in the machine learning field have increased a lot through the last couple of years, we are able to benefit from them;
- This mechanism could provide a low cost substitute to current intricate *ad hoc* models.

For testing the model, we chose Google as our ranking expert and compared the performance of HITS and XHITS in relation to it. The gains of XHITS' model over HITS' are substantial as shown in the experimental result, over 200 % gain of quality. One promising direction for future work that we are exploring is to extend this work by changing the benchmark and apply the XHITS to GOV2 collection and compare the performance with others ranking algorithms already explored and reported in the literature.

ACKNOWLEDGEMENTS

Part of this work is supported by Brazilian Army Technology Center - CTEEx. We give our thanks to all people who have contributed to this research and development.

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