

# A BAYESIAN METHOD FOR THE DETECTION OF EPISTASIS IN QUANTITATIVE TRAIT LOCI USING MARKOV CHAIN MONTE CARLO MODEL COMPOSITION WITH RESTRICTED MODEL SPACES

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Abstract: Epistasis or the interaction between loci on a genome is of great interest to geneticists. Herein, a powerful Bayesian method utilizing Markov chain Monte Carlo model composition approach using restricted spaces is developed for identifying epistatic effects in Recombinant Inbred Lines (RIL). The method is verified through a simulation study and applied to an *Arabidopsis thaliana* data set with cotyledon as the quantitative trait.

## 1 INTRODUCTION

Quantitative Trait Loci (QTL) analysis is concerned with determining which region on a genome that explains or controls a quantitative trait. However, in many instances an interaction between regions or loci may provide a better explanation for a trait than regions having a strictly additive influence. This interaction between loci on a genome is known as *epistasis*. To study QTLs, organisms generated by recombinant inbreeding are often used. Recombinant Inbred Lines (RIL) are organisms that have been repeatedly mated with siblings and themselves in order to create an inbred line whose genetic structure is a combination of the original parent organisms. These RILs provide a mechanism to reduce environmental and individual effects. Furthermore, these homozygous organisms help simplify the search for the loci on the genome has influence over a trait. This simplification is due to fact that at each locus one does not need to know the actual allele. Instead, one can track whether the allele at a locus came from parent A or parent B. For a complete review of RILs see (Broman, 2005).

Several methods have been developed to detect and evaluate epistatic effects for continuous traits.

Multiple Interval Mapping (MIM) proposed by (Kao *et al.*, 1999) based on fitting a multiple regression model that has both main effect terms as well as interactions and employing a non-Bayesian search method. (Carlborg, 2004) use a genetic algorithm to search for the loci and epistatic effects. (Hansen and Wagner, 2001) propose a theoretical framework for higher order interactions. (Kao and Zeng, 2001) use the framework of (Cockerham, 1954) to partition the variance for known main and epistatic effects in order to understand the contribution of each with no search method. (Zeng *et al.*, 2005) and (Wang and Zeng, 2006) use (Cockerham, 1954) partition the variance when epistatic effects with multiple alleles are present however no search method is presented in this work either. (Hanlon and Lornez, 2005) use an optimization approach to find combinations of epistatic effects that best represent the trait of interest based on squared error distance.

To avoid this problem of model selection (Broman and Speed, 2002) use Markov Chain Monte Carlo Model Composition ( $MC^3$ ) to search for the main effects (additive models) that contribute to the trait. This procedure is a variant of reversible jump Markov chain Monte Carlo by (Green, 1995). (Boone *et al.*,

2006) extend this to restricted model spaces to allow for more loci than observations. (Yi *et al.*, 2003), (Yi *et al.*, 2005), (Yi *et al.*, 2007a), (Yi *et al.*, 2007b) use the  $MC^3$  framework with various restrictions on the model space to search for main and epistatic effects. However, (Yi *et al.*, 2003), (Yi *et al.*, 2005), (Yi *et al.*, 2007a), (Yi *et al.*, 2007b) and the R/qtlbim software of (Yandell *et al.*, 2007) do not require that the main effect terms corresponding to the epistatic effects be present in the model. Furthermore, (Broman and Speed, 2002), (Yi *et al.*, 2003), (Yi *et al.*, 2005), (Yi *et al.*, 2007a), (Yi *et al.*, 2007b) and (Yandell *et al.*, 2007) employ information criteria such as AIC or BIC as the basis for the  $MC^3$  search. (Boone *et al.*, 2005) show that while BIC is an asymptotically correct approximation for posterior model probabilities, in the low to moderate sample size case BIC performs poorly.

The goal of this work is to explore a  $MC^3$  algorithm with restricted model spaces that require the main effect terms corresponding to the epistatic be present in the model. In addition, this article proposes conditional activation probabilities as a tool to evaluate epistatic effects in models where the corresponding main effects are included. Furthermore, to avoid the use of information criterion such as AIC or BIC as the basis of the  $MC^3$  search.

Current methods for assessing epistasis use frequentist tests which are inherently model dependent. This work uses activation probabilities (proposed by (Boone *et al.*, 2006) for use in QTLs), defined in Section 2.2 for each of the main and epistatic effects to determine the marginal posterior probability of each effect regardless of which model is chosen. Figure 1 shows an example heatmap of the activation probabilities that may occur when epistasis is present. Activation probabilities along the diagonal correspond to the main effect of the locus. The off diagonal activation probabilities correspond to epistatic effects. Notice that by looking along the diagonal the main effects appear to be at locus 12, locus 26 and locus 35 as the (12, 12), (26, 26) and (35, 35) regions have high probability. Furthermore one can look at the off diagonal and see that loci 12 and 26 appear to have an epistatic effect as well as noted by high probability in the (12, 26) region. However, loci 12 and 35 and loci 26 and 35 do not appear to have an epistatic effect due to low probability in the regions common to (12, 35) and (26, 35) on the heatmap.

Section 2 defines the model, basic search strategy, activation probabilities and conditional activation probabilities. Section 2.3 explains the neighborhood definition and search strategy under restricted model spaces. Section 3 gives a simulation study showing

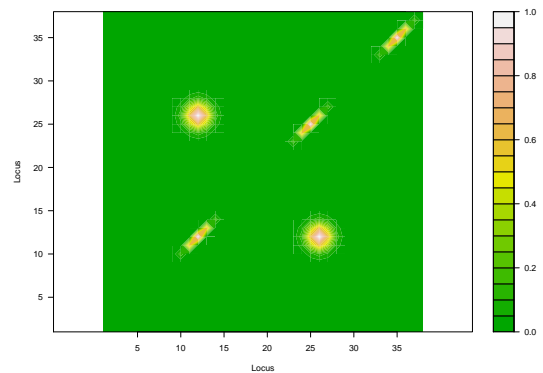


Figure 1: Simulated heatmap of activation probabilities for main effect and epistatic effects. Activation probabilities along the diagonal correspond to main effects and off diagonal correspond to epistatic effects.

the efficacy of the method for detecting both main effects and two-way interaction effects. Section 4 considers the *Arabidopsis Thaliana* as an example. The dataset for this model organism has 158 lines of RIL and 38 markers (loci) and cotyledon opening angle is the quantitative trait of interest.

## 2 BAYESIAN MODEL SEARCH

### 2.1 Model Definition

Let  $y_i$  be the quantitative trait for the  $i^{\text{th}}$  observation. For each of the  $p$  loci  $l_1, l_2, \dots, l_p$  the parentage of the allele is recorded as A if the allele came from parent A and B if the allele came from parent B. However, in some instances the allele is not determined which needed to be reflected in the analysis. For the  $i^{\text{th}}$  observation and locus  $l_j$  this information can be coded into  $X_{ij}$  as:

$$X_{ij} = \begin{cases} 1, & \text{allele } l_j \text{ is from parent A} \\ -1, & \text{allele } l_j \text{ is from parent B} \\ 0, & \text{allele } l_j \text{ is undetermined} \end{cases} \quad (1)$$

Here the  $X_{ij}$  correspond to the main effects. For the epistatic effects (two-way interaction) this produces the interaction between loci  $l_j$  and  $l_k$  as:

$$X_{ij}X_{ik} = \begin{cases} 1, & \text{alleles } l_j \text{ and } l_k \text{ from same parent} \\ -1, & \text{alleles } l_j \text{ and } l_k \text{ from different parents} \\ 0, & \text{allele } l_j \text{ or } l_k \text{ is undetermined} \end{cases} \quad (2)$$

Using a traditional first order model with a two-way multiplicative interaction terms the model is de-

defined as:

$$y_i = \mu + \sum_{j=1}^p \beta_j X_{ij} I_{P_c}(l_j) + \sum_{k < j} \beta_{jk} X_{ij} X_{ik} I_{P_c}(l_j) I_{P_c}(l_k) + \varepsilon_i. \quad (3)$$

where  $\varepsilon_i \sim N(0, \sigma_c^2)$ ,  $P_c$  is the set of loci  $l_j$  in model  $M_c$ , and  $I_{P_c}$  is an indicator function that takes the value 1 if  $l_j \in P_c$  and 0 otherwise. Here  $\beta_j$  corresponds to the main effect of locus  $l_j$  and  $\beta_{jk}$  is the epistatic effect between loci  $l_j$  and  $l_k$ .

## 2.2 Bayesian Model Averaging

In a model space  $\mathcal{M}$  with  $|\mathcal{M}|$  models, the posterior probability of model  $M_c$  given the data  $\mathcal{D}$  can be computed via Bayes' Theorem:

$$P(M_c | \mathcal{D}) = \frac{P(M_c)P(\mathcal{D} | M_c)}{\sum_{t=1}^{|\mathcal{M}|} P(M_t)P(\mathcal{D} | M_t)}. \quad (4)$$

The marginal probability of the data  $\mathcal{D}$  given model  $M_c$ ,  $P(\mathcal{D} | M_c)$  is involved in computing (4) and can be calculated using:

$$P(\mathcal{D} | M_c) = \int P(\theta_c | M_c) P(\mathcal{D} | \theta_c, M_c) d\theta_c, \quad (5)$$

where  $\theta_c$  is the parameter vector corresponding to model  $M_c$ . Evaluating the integral in (5) can be complicated. Approximations such as the Laplace approximation and the approximation based on Schwarz Bayesian Information Criterion (BIC) could be employed. However, in the linear model case, as in equation (3), where the coefficient vector for model  $M_c$ ,  $\beta_c \sim N(\mu_c, V_c)$  and  $\sigma_c^2 \sim Inv - \chi^2(\nu, \lambda)$  prior is used, an analytic expression for (5) is:

$$\begin{aligned} P(\mathcal{D} | \mu_c, V_c, \nu, X_c, M_c) &= \frac{\Gamma(\frac{\nu+n}{2}) (\nu\lambda)^{\frac{\nu}{2}}}{\pi^{\frac{n}{2}} \Gamma(\frac{\nu}{2}) |I + X_c V_c X_c'|^{1/2}} \\ &\times [\lambda\nu + (Y - X_c \mu_c)'] \\ &\times (I + X_c V_c X_c')^{-1} \\ &\times (Y - X_c \mu_c)^{-\frac{\nu+n}{2}}, \end{aligned} \quad (6)$$

where  $\mu_c$  and  $V_c$  are the mean and variance, respectively, and  $\nu$  and  $\lambda$  are the degrees of freedom, and location parameter, respectively. This work will employ (6) for computing (5) versus any information criterion based approximations.

In cases where the model space is sufficiently large, calculating (5) for each model is computationally infeasible. A stochastic search through the model space can be performed using a metropolis-hastings approach. For more on metropolis-hastings sampling see (Chib and Greenberg, 1995), (Bolstad, 2010).

This can be accomplished by constructing neighborhoods around the current model  $M_c$ . Typically, the neighborhoods  $nbd(M_c)$  consist of all models with one additional term than model  $M_c$  and all models with one less term than model  $M_c$ . For a candidate model  $M_t \in nbd(M_c)$  the probability,  $\alpha$ , of acceptance of model  $M_t$  is given by.

$$\alpha = \min \left\{ 1, \frac{P(M_t)P(\mathcal{D} | M_t) q(M_t | M_c)}{P(M_c)P(\mathcal{D} | M_c) q(M_c | M_t)} \right\}, \quad (7)$$

where  $q(M_t | M_c)$  is the probability that the candidate model is  $M_t$  is selected for consideration given the current state is model  $M_c$ . Note the neighborhood structure mentioned above is not appropriate when the main effect terms are required to be in the model whenever an epistatic term is in the model. (Yi *et al.*, 2003), (Yi *et al.*, 2005), (Yi *et al.*, 2007a), (Yi *et al.*, 2007b) and (Yandell *et al.*, 2007) allow the neighborhood to be all models with one main effect term more or less than  $M_c$  and all models with one epistatic effect more or less than  $M_c$ . Since they do not require that when an epistatic term is in the model that the corresponding main effect terms be in the model as well, this is a reasonable neighborhood structure however it is different than the structure proposed here. They also further propose that the neighborhoods could include only loci that are near to current locus on the genome.

Once the posterior model probabilities have been computed activation probabilities can be used to assess the impact of predictor  $X_j$  and can be computed via:

$$P(\beta_j \neq 0 | \mathcal{D}) = \sum_{c=1}^{|\mathcal{M}|} P(\beta_j \neq 0 | \mathcal{D}, M_c) P(M_c | \mathcal{D}). \quad (8)$$

Activation probabilities are different from the traditional p-value in that large values indicate significance versus small values. In addition, activation probabilities do not depend on a specific model as do p-values. The activation probabilities can be calculated via  $MC^3$  as defined in section 2.3.

Activation probabilities will have a problem detecting two-way interactions when the main effect terms are required to be in the model in order for the two-way interaction term to be present. This induces the following inequalities:

$$\begin{aligned} P(\beta_{jk} | \mathcal{D}) &\leq P(\beta_j | \mathcal{D}) \\ P(\beta_{jk} | \mathcal{D}) &\leq P(\beta_k | \mathcal{D}). \end{aligned} \quad (9)$$

Hence, using the standard activation probabilities for two-way interaction effects will produce probabilities that are damped. In order to amplify the activation probabilities of the two-way interaction effects one

can use conditional activation probabilities. Conditional activation probabilities can also be obtained by:

$$\begin{aligned} P(\beta_{jk} \neq 0 | \beta_j \neq 0, \beta_k \neq 0, \mathcal{D}) & \quad (10) \\ &= \frac{P(\beta_{jk} \neq 0, \beta_j \neq 0, \beta_k \neq 0 | \mathcal{D})}{P(\beta_j \neq 0, \beta_k \neq 0 | \mathcal{D})}, \end{aligned}$$

provided that  $P(\beta_j \neq 0, \beta_k \neq 0 | \mathcal{D}) > 0$ . In practice one should only consider conditional activation probabilities when both  $P(\beta_j | \mathcal{D})$  and  $P(\beta_k | \mathcal{D})$  are considerably large. In cases where  $P(\beta_j | \mathcal{D})$  or  $P(\beta_k | \mathcal{D})$  are small then unreasonably large inflations to the conditional activation probabilities will occur and hence the result in incorrect inferences.

### 2.3 Restricted Model Space

A simple approach to defining the neighborhoods of a model  $M_c$  is to include all models that add an additional term or drop an existing term. However, this violates a model that require both main effect terms need to be present in the model in order for the corresponding two-way interaction to be added. Furthermore, the model need not contain all interaction terms possible. Notice this creates a large model space. For the first order models with  $p$  predictors the size of the model space is  $2^p$ . However with the addition of interaction terms, the size grows considerably more. In a dataset with 30 loci, a full model with all first order terms and two-way interaction terms will have 465 terms. This can be prohibitively large for most datasets and algorithms. If the model space is restricted to  $r < p$  predictors and the corresponding epistasis terms, then any model considered will not have nearly as many terms. If  $r$  is chosen wisely, then the researcher can ensure that each model under consideration has sufficient degrees of freedom to be estimated.

Furthermore, cases where linear dependencies exist among the predictors estimation can be complicated. One approach to address this issue is to assign  $P(M_c) = 0$  to all models where linear dependencies exist among the predictors. Hence removing all multicollinear models from consideration. Any time there are multicollinear terms an index will need to be created in order to keep track of any *aliased* terms. This aliasing can cause problems when there is a large effect size for the aliased terms.

The use of restricted model spaces allows for the assessment of all candidate variables, however it restricts the number of candidate variables that may be simultaneously considered in a single model. (Yi *et al.*, 2003), (Yi *et al.*, 2005), (Yi *et al.*, 2007a), (Yi *et al.*, 2007b) and (Yandell *et al.*, 2007) use two restrictions one for the number of main effect terms and one

for the number of epistatic terms allowed in the model simultaneously. They also give a simple guideline to determine the size of each restriction. They suggest to choose the restriction  $r = m + 2\sqrt{m}$  where  $m$  is the a priori expected number of main effects. Similarly the same formula can be employed where  $m$  is the expected number of epistatic effect.

To search through the restricted model space,  $MC^3$  can be employed using equation (7). Note that  $q(M_i | M_c)$  must be determined to move through the sample space. Let  $nbd(M_c)$  be all models with one main effect term more, one valid interaction term more, one main effect term less and one interaction term less than model  $M_i$ . Denote adding a main effect term as AMT, adding an interaction effect term as AIT, dropping a main effect term as DMT and dropping an interaction effect term as DIT. The probability of each of these actions depends on the attributes of the current model  $M_c$ . Let  $\gamma_c$  and  $\phi_c$  be the number of main effect terms and number of interaction terms in  $M_c$ , respectively. In order to ensure that all models in  $nbd(M_c)$  are equally likely, the probability of each action, AMT, AIT, DMT and DIT need to be determined. Let  $\Omega = \{AMT, AIT, DMT, DIT\}$  be an action space. Once these probabilities have been calculated, the following procedure allows for each of the models in  $nbd(M_c)$  to be sampled to be candidate model. First determine,  $P(AMT)$ ,  $P(AIT)$ ,  $P(DMT)$  and  $P(DIT)$ , and choose an action with the corresponding probability. Then select with equal probability a model that is in  $nbd(M_c)$  and corresponds to the action. This procedure ensures that all models in  $nbd(M_c)$  have equal probability. Having all models in  $nbd(M_c)$  equally likely will be necessary in computing  $q(M_c | M_i)$ .

For  $\gamma_c = 0$ , only a main effect term may be added since no interaction terms are in the model. Hence the probability distribution for  $\Omega$  is:

$$\begin{aligned} P(AMT) &= 1, P(DMT) = 0, \\ P(AIT) &= 0, P(DIT) = 0. \end{aligned} \quad (11)$$

For  $\gamma_c = 1$ , the one of the  $p - 1$  main effect terms not in the model may be added or the one main effect term in the model may be dropped and no interaction terms are allowed in this model. Hence the probability distribution for  $\Omega$  is:

$$\begin{aligned} P(AMT) &= \frac{p-1}{p}, P(DMT) = \frac{1}{p}, \\ P(AIT) &= 0, P(DIT) = 0. \end{aligned} \quad (12)$$

For  $2 \leq \gamma_c \leq r$ , no restrictions are involved. Hence, all actions in  $\Omega$  are allowed. Hence, the prob-



ability distribution for  $\Omega$  is:

$$\begin{aligned} P(AMT) &= \frac{p-\gamma_c}{p+\binom{\gamma_c}{2}}, & P(AIT) &= \frac{\binom{\gamma_c}{2}-\phi_c}{p+\binom{\gamma_c}{2}}, \\ P(DMT) &= \frac{\gamma_c}{p+\binom{\gamma_c}{2}}, & P(DIT) &= \frac{\phi_c}{p+\binom{\gamma_c}{2}}. \end{aligned} \quad (13)$$

For  $\gamma_c = r$ , due to the restriction that no more than  $r$  main effect terms may be in a model at a single time, no main effect terms may be added. However, main effect terms may be dropped and interaction terms may be added or dropped. Hence, the probability distribution for  $\Omega$  is:

$$\begin{aligned} P(AMT) &= 0, & P(AIT) &= \frac{\binom{r}{2}-\phi_r}{\binom{r}{2}+k}, \\ P(DMT) &= \frac{r}{\binom{r}{2}+r}, & P(DIT) &= \frac{\phi_c}{\binom{r}{2}+r}. \end{aligned} \quad (14)$$

Since each model in  $nbd(M_c)$  is equally likely to be sampled,  $q(M_t|M_c)$  can easily be formed. For example, let  $M_t$  and  $M_c$  be such that  $\gamma_t = \gamma_c + 1$  where  $\gamma_t < r$  and  $\gamma_c > 2$ . Then this corresponds to the action AMT and the probability of candidate model  $M_t$  given that the current model is  $M_c$  is one out of the number of models in  $nbd(M_c)$ , specifically,  $q(M_t|M_c) = \left(p + \binom{\gamma_c}{2}\right)^{-1}$  and similarly  $q(M_c|M_t) = \left(p + \binom{\gamma_t}{2}\right)^{-1}$ . Hence the ratio of the probability of candidate models for this case is:

$$\frac{q(M_t|M_c)}{q(M_c|M_t)} = \frac{p + \binom{\gamma_t}{2}}{p + \binom{\gamma_c}{2}}.$$

### 3 SIMULATION STUDY

To validate this approach, loci information from *Arabidopsis thaliana* Bay-0  $\times$  Shadara was used. Figure 2 illustrates the genetic map of the *Arabidopsis thaliana* Bay-0  $\times$  Shadara, which has five chromosomes and on each chromosome each locus where the parentage of the allele has been determined is marked. There was a total of 38 loci used for this simulation study and 158 lines.

To assess the ability of the method to detect both main effects and epistatic effects a simulation study

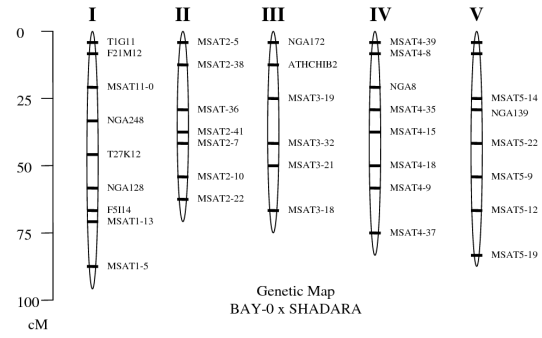


Figure 2: Genetic map of the *Arabidopsis thaliana* Bay-0 by Shadara.

was conducted. Using the loci matrix from the *Arabidopsis thaliana* dataset two loci  $X_A$  and  $X_B$  were randomly selected from the possible loci and the following model was used to generate the data:

$$y_i = \delta X_{Ai} + \delta X_{Bi} + \delta X_{Ai}X_{Bi} + \epsilon_i, \quad (15)$$

where  $\delta$  is the effect size,  $\epsilon_i \sim N(0, 1)$ . Each dataset contained a sample size of 158 observations. Effect sizes of 0, 1/2, 1, 3/2, 2, 5/2, 3, 7/2, 4, 9/2 and 5 were considered. Each of these effect sizes was repeated 10 times.

Using the data set and the method proposed the following probabilities were calculated:  $P(X_A|\mathcal{D})$ ,  $P(X_B|\mathcal{D})$ ,  $P(X_{AB}|\mathcal{D})$  and  $P(X_{AB}|X_A, X_B, \mathcal{D})$ . These were calculated for 100 simulated data sets. Using the following prior distributions  $\beta_j \sim N(0, 200)$  and  $\sigma^2 \sim \chi^2(1)$  for the model parameters and  $P(M_i)$  is uniform over the all models subject to the restriction of  $r = 10$ . For each simulated data set a chain of 16,000 samples were taken from the posterior distribution of the models, with the first 1,000 samples discarded as burn-in samples. The activation probabilities were calculated using the remaining 15,000 samples.

Figure 3 show boxplots the main effect activation probabilities versus the effect size from the simulated datasets. Notice that for effect sizes of 0 and 1/2 the activation probabilities are low indicating that not much evidence exists for the main effect at that locus. However, for effect sizes at and above 1 the activation probabilities are quite high, typically above 0.8. It should be noted that activation probabilities are not associated with the idea of a p-value and hence cannot be interpreted as such. Furthermore, the choice of cutoff values for activation probabilities and what is deemed statistically significant, in the Type I and Type II error sense, has not been studied. However, we should notice that the activation probabilities for effect sizes at and above 1 are much larger than those when the effect size is 0. Hence, one could feel con-

vident that the locus is important for influencing the observed trait.

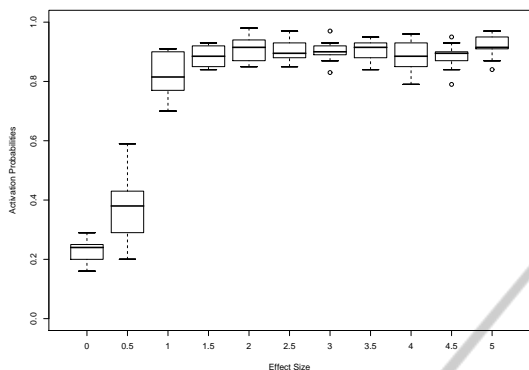


Figure 3: Boxplots of main effect activation probabilities for effect sizes 0, 1/2, 1, 3/2, 2, 5/2, 3, 7/2, 4, 9/2 and 5 using simulated data sets.

Figure 4 show boxplots for activation probabilities of the epistatic effects and the conditional activation probabilities for epistatic effects versus the effect size. Notice that in both plots that both the activation probabilities and the conditional activation probabilities are low for effect sizes 0 and 1/2 indicating that the epistatic effect of the two loci have no minimal effect on the observed trait. However, notice that for effect sizes larger than 1 the conditional activation probabilities are considerably higher than the standard activation probabilities. Again there has been no studies of cutoff values for activation probabilities nor conditional activation probabilities. Looking at both the activation probabilities and conditional activation probabilities with reference to effect size 0 one could feel confident that the two loci work in combination to influence the observed trait.

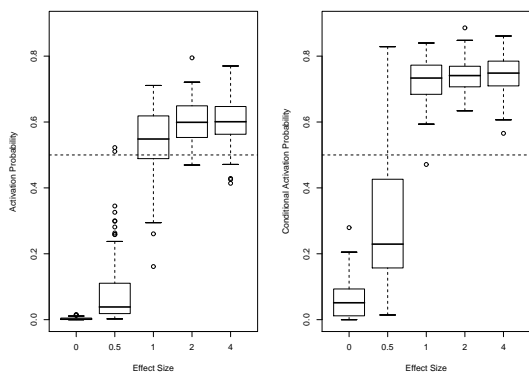


Figure 4: Boxplots of epistatic effect activation probabilities (left) and conditional activation probabilities for epistatic effects (right) for effect sizes 0, 1/2, 1, 3/2, 2, 5/2, 3, 7/2, 4, 9/2 and 5 using 100 simulated data sets per effect size. Dashed line at 1/2 is for reference.

## 4 EXAMPLE

The *Arabidopsis thaliana* is a model plant for genetic experiments in that it is easily genetically manipulated. The response of interest is the angle cotyledon opening for 158 lines; the values range between 0 and 180. The cotyledon is the is the first embryonic leaves on a seedling plant. The wider the opening angle the more viable the mature plant. For each line at each of the chromosomal locations (markers) a value of 1 or -1 corresponding to whether the marker at that location came from parent A or parent B, respectively. With this data and using an unrestricted model space the largest model would have 741 terms. Hence, many models are not able to be fit. By restricting the model space to  $r = 10$  the largest model would have 55 terms and thus, all models have enough observations to be estimated.

To determine if any aliasing between the main effects and interaction terms occurred the data was screened. This screening showed that no interaction terms are aliased with any main effect term. Hence, conclusions about the main effect terms will not be confounded with any epistatic effects. An additional screen of the data was performed to determine if there is aliasing between any interaction effects. Aliased interaction effects were noted for consideration during posterior inferences.

For this example, the exact marginal posterior probability of the data given model  $M_c$  was computed using equation (6) and the proposed  $MC^3$  method with restricted model space was utilized. For each model under consideration the prior distributions for the model parameters were defined as:  $\beta_{ij} \sim N(0, 200)$  for all  $j$  and  $\beta_{jk} \sim N(0, 200)$  for all interaction terms  $jk$  in model  $i$ ; for  $\sigma^2, \lambda = 1$  and  $v = 1$  are used. Note that when  $v = 1$  the  $Inv - \chi^2_v$  has infinite mean and variance. Hence, should be relatively uninformative. For each model  $M_c$  where multicollinearity does not occur, the prior probability  $P(M_c)$  is chosen uniform across this space. Thus, a priori, no model is preferred over another.

Using the restriction  $r = 10$ , 25 chains of 11,000 were run with a burn in of 1,000 samples using overdispersed starting models resulting in 250,000 samples. The number of visits to model  $M_c$  was recorded and the probability of model given the data  $P(M_c|D)$  is estimated as the number of visits to model  $M_c$  divided by the length of the chain. The probabilities appeared to converge after 15 chains, indicating convergence. Using these probabilities the activation probabilities  $P(\beta_j \neq 0|D)$  are computed for each main and epistatic effect. Figure 5 shows a heat map of epistatic probabilities. Notice that the highest acti-

vation probability locus on the heat map is at locus 18 (ATHCHIB2) and no epistatic, off diagonal, effects have high activation probability.

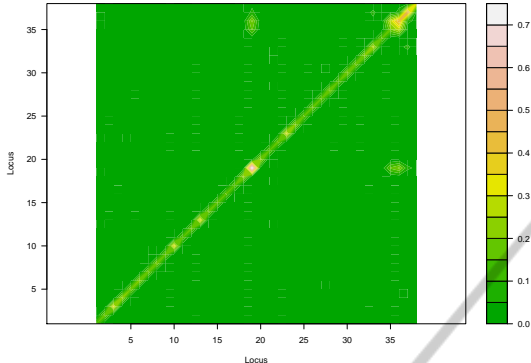


Figure 5: Heat map of epistatic probabilities.

The activation probabilities for the 3 highest loci, ATHCHIB2, MSAT5-9 and MSAT5-22 are as follows:  $P(ATHCHIB2|\mathcal{D}) = 0.741$ ,  $P(MSAT5 - 9|\mathcal{D}) = 0.481$  and  $P(MSAT5 - 22|\mathcal{D}) = 0.445$ . This suggests that the following epistatic effects should be considered:  $ATHCHIB2 \times MSAT5 - 9$ ,  $ATHCHIB2 \times MSAT5 - 22$  and  $MSAT5 - 9 \times MSAT5 - 22$ . Previous studies have shown ATHCHIB2 to be a locus associated with cotyledon opening (Boone *et al.*, 2006). Hence the results agree with biological expectations. In order to more accurately locate the locus associated with cotyledon opening a dense map of genes near ATHCHIB2 should be undertaken.

Table 1: Activation probabilities and conditional activation probabilities of epistatic effects between locus  $l_j$  and locus  $l_k$ .

$l_i$	$l_j$	$P(l_{ij} \mathcal{D})$	$P(l_{ij} l_i, l_j, \mathcal{D})$
ATHCHIB2	MSAT5-9	0.070	0.243
ATHCHIB2	MSAT5-22	0.061	0.191
MSAT5-9	MSAT5-22	0.062	0.135

## 5 DISCUSSION

The proposed method for detecting epistasis has the ability to determine which main effects as well as which two-way interaction effects are present in a dataset as evidenced by the simulation study. The method was applied to the *Arabidopsis thaliana* data and no epistatic effects were found with respect to cotyledon opening angle. However, the known locus for controlling cotyledon opening was detected, ATHCHIB2. The search method was employed in a

situation where the number of parameters in the full model far exceeded the number of observations. The search was done in a manner that allowed for sufficient degrees of freedom for each model under consideration.

A study of epistatic models which do not require the first order terms to be present should be considered as well. This may allow for better detection of epistatic effects as the model search does not need to first add a main effect in order to later include the epistatic term. In this case the model space would be reduced by  $2^p$  models. However, if all other interaction terms are equally likely to be added to the model, the Metropolis-Hastings step may have low acceptance probability and convergence of the  $MC^3$  algorithm may be slow. In addition, any loci that have effects that are not in interaction with other loci may not be detected. Hence, reducing the utility of the method.

Caution should be used when using restricted model spaces. The method works best when it is believed that only a few loci control the trait of interest. In cases where it is believed that a large number of loci control the trait of interest, especially when this exceeds the restriction on the model space, then the search method maybe come very ineffective at assessing both the main effect as well as the epistatic effects. Since the models at the restriction boundary will have high posterior model probabilities it may be difficult to move through regions of lower probability towards even more probable models. In most cases in genetics it is believed that only a few loci control the trait of interest.

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