

Improving the Performance of Speaker Verification Systems under Noisy Conditions using Low Level Features and Score Level Fusion

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Abstract: This paper provides an overview of low-level features for speaker recognition, with an emphasis on the recently proposed MFCC variant based on asymmetric tapers (MFCC asymmetric from now on); which has proven high noise robustness in the context of speaker verification. Using the TIMIT corpus the performance of the MFCC-asymmetric is compared with: the standard Mel-Frequency Cepstral Coefficients (MFCC) and The Linear Frequency Cepstral Coefficients (LFCC) under clean and noisy environments. To simulate real world conditions, the verification phase was tested with two noises (babble and factory) at different Signal-to-Noise Ratios (SNR) issued from NOISEX-92 database. The experimental results showed that MFCCs-asymmetric tapers (k=4) outperform other features in noisy condition. Finally, we have investigated the impact of consolidating evidences from different features by score level fusion. Preliminary results show promising improvement on verification rate with score fusion.

1 INTRODUCTION

In the last five decades people have come forward to investigate various aspects of speech such as mechanical realization of speech signal (Fry, 1959), human machine interaction (Teeni et al., 2007), speech and speaker recognition (identification and verification) (Sambur, 1972). In this context, a speech signal is usually the bearer of a message to another person. The word can contain a lot of information such as the language spoken by the speaker or even indications of age or speaker's identity. However, speaker verification is one biometric system that uses speech as a tool for detecting the identity of the person who produced it.

Speaker verification systems typically use acoustic parameters calculated from short-term spectrum characteristics of the signal and the envelope of the spectrum. In this paper, the performance of MFCC-asymmetric (Alam et al., 2012); (Juan et al., 2011) is compared with: the standard Mel-Frequency Cepstral Coefficients (MFCC) (Harris, 1978) and the Linear Frequency Cepstral Coefficients (LFCC) (Xing et al., 2009) under clean and noisy environments. The focus of this work is to evaluate the effect of front-end on the

performance of our speaker verification system based on gaussian mixture model- universal background model (GMM-UBM) as a baseline classifier under clean and noisy environments. The Gaussian mixture model (GMM) with universal background model UBM, has proven to be extremely efficient for characterizing speaker identity at the acoustic level (Xing et al., 2009). In this approach, speaker models are obtained from the normalization of a universal background model (UBM) (Reynolds et al., 2000). The UBM is usually trained by means of the Expectation-Maximization (EM) algorithm from a background dataset, which includes a wide range of speakers, languages (for Multilanguage application), communication channels, recording devices, and environments. The GMM-UBM (Reynolds et al., 2000) becomes a standard technique for text-independent speaker verification due to its reliable performance, especially after the introduction of the maximum a posteriori adaptation coupling the client and the UBM model.

The contribution of this paper is twofold. First, presenting a comparative study of the classical and recently proposed short-term features. Second, investigating the possibility of improving the performance of speaker verification systems by

score level fusion on different features.

The outline of paper is as follows. In sections 2, we describe the different feature vectors used in this work. At section 3, we give the experimental protocol adopted and the results that found at section 4. Finally, a conclusion is given in Section 5.

2 FEATURE EXTRACTION OVERVIEW

The speech signal continuously changes due to articulatory movements and therefore, the signal must be analyzed within short frames of about 20–30 ms duration. Within this interval, the signal is assumed to remain stationary and a spectral feature vector is provided for each frame.

2.1 Mel-Frequency Cepstral Coefficients (MFCCs) and Linear Frequency Cepstral Coefficients (LFCCs)

The mel-frequency cepstral coefficients (MFCCs) (Harris, 1978) were introduced in early 1980s for speech recognition applications and since then have also been adopted for speaker identification applications. A sample of speech signal is first extracted through a window. Typically, two parameters are important for the windowing procedure: the duration of the window (ranges from 20–30 ms) and the shift between two consecutive windows (ranges from 10–15 ms) (Harris, 1978) The values correspond to the average duration for which the speech signal can be assumed to be stationary or its statistical and spectral information does not change significantly. The speech samples are then weighed by a suitable windowing function, such as, Hamming or Hanning window (Harris, 1978), that are extensively used in speaker verification. The weighing reduces the artifacts (such as side lobes and signal leakage) due to the use of a finite duration window size for analysis. The magnitude spectrum of the speech sample is then computed using a fast Fourier transform (FFT). For a discrete signal $\{x[n]\}$ with $0 < n < N$, where N is the number of samples of an analysis window, is the sampling frequency, the discrete Fourier transform (DFT) is used and is given by equation below:

$$S(f) = \left| \sum_{t=0}^{N-1} w(t)x(t)e^{-i2\pi ft / N} \right|^2 \quad (1)$$

Where $i = \sqrt{-1}$ is the imaginary unit and $f = 0, 1, \dots, N-1$ denotes the discrete frequency index. Here, $w = [w(0) \dots w(N-1)]^T$ is a time-domain window function which usually is symmetric and decreases towards the frame boundaries. Then, $S(f)$ is processed by a bank of band-pass filters. The filters that are generally used in MFCC computation are triangular filters (Moore, 1995), and their center frequencies are chosen according a logarithmic frequency scale, also known as Mel-frequency scale. The filter bank is then used to transform the frequency bins to Mel-scale bins by the following equations:

$$m_y[b] = \sum_f w_b[f] |S[f]|^2 \quad (2)$$

where w_b is the b^{th} Mel-scale filter's weight for the frequency f and $S[f]$ is the FFT of the windowed speech signal. The rationale for choosing a logarithmic frequency scale conforms to the response observed in the human auditory system that has been validated through several biophysical experiments (Moore, 1995). The Mel-frequency weighted magnitude spectrum is processed by a compressive non-linearity (typically a logarithmic function) which also models the observed response in a human auditory system. The last step in MFCC computation is a discrete cosine transform (DCT) which is used to de-correlate the Mel-scale filter outputs. A subset of the DCT coefficients are chosen (typically the first and the last few coefficients are ignored) and represent the MFCC features used in the enrollment and the verification phases. The Linear Frequency Cepstral Coefficients (LFCCs) (Xing et al., 2009) are similar to MFCCs, with a difference in the structure of the Mel filter bank. In the high frequency region, the Mel filters was replaced by a linear filter bank in order to capture more spectral details in this region.

2.2 MFCCs based on Asymmetric Tapers

Usually, speaker/speech recognition systems for short-time analysis of a speech signal use standard symmetric- tapers such as Hamming, Hann, etc. These tapers have a poor magnitude response under mismatched conditions and a larger time delay (Alam et al., 2012). One elegant technique for reducing the time delay and enhancing the magnitude response under noisy conditions is to

replace symmetric tapers by asymmetric tapers (Juan et al., 2011). The method based on asymmetric tapers is an extension of the conventional windowed using symmetric tapers. From a symmetric taper $w_s(n)$ of length N , the instantaneous phase $\theta(n)$ computed by applying a Hilbert transform to the symmetric taper. Then, the asymmetric taper is $w_{at}(n)$ obtained as:

$$w_{at}(n) = cw_s(n)e^{k\theta(n)}, 0 \leq n \leq N-1 \quad (3)$$

where n is the time index, $w_s(n)$ is the symmetric taper of length N , $e^{k\theta(n)}$ is an asymmetric function, k is a parameter that controls the degree of asymmetry, and c is the normalizing constant given by

$$c = \frac{\max(w_s(n))}{\max(w_s(n)e^{k\theta(n)})}, 0 \leq n \leq N-1 \quad (4)$$

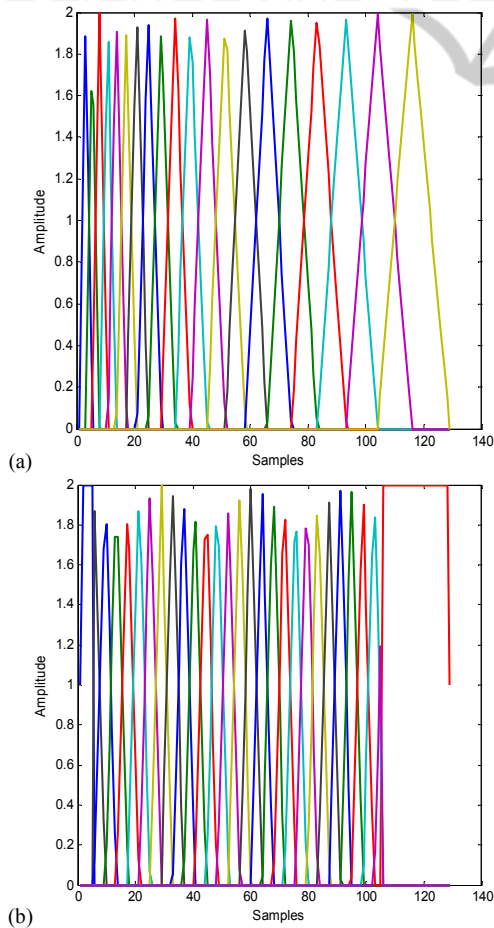


Figure 1: a) Mel filterbanks, b) Linear filterbanks.

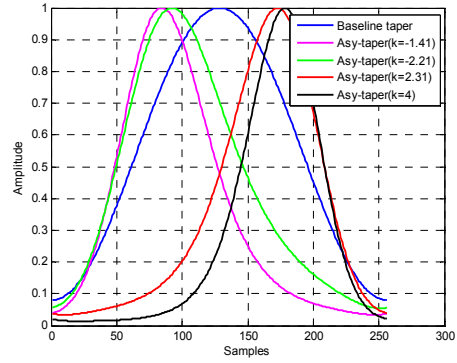


Figure 2: Comparison between symmetric Hamming and asymmetric tapers.

3 SPEAKER VERIFICATION PROTOCOL

Speaker verification experiments are carried out on the TIMIT corpus which consists of read speech sampled at 16 kHz. It involves 168 speakers with 168 client scores and 28056 impostor scores. For each target speaker, approximately 15seconds of training data is available whereas duration of the test utterances is 9 seconds. Gaussian mixture model with the universal background model (GMM-UBM) (Reynolds et al., 2000) is used as the classifier. Otherwise, for each enrolment utterance, a GMM with 32 components (Reynolds et al, 2000) is trained with the extracted spectral features, using Expectation Maximization algorithm (EM) (Kinnunen et al., 2009). We normalized the client GMM likelihood by the universal background model (UBM) likelihood, which is widely used in speaker verification. Our UBM is a GMM with 128 components trained via EM algorithm using speech from a large number of speakers (42 min). In parameterization phase, we specified the feature space used. Indeed, as the speech signal is dynamic and variable, we presented the observation sequences of various sizes by vectors of fixed size. Each vector is given by the coefficients Mel Cepstrum MFCC (23 coefficients), extracted from the middle window every 10 ms. In Asymmetric taper MFCCs features (23 coefficients), we used different values of the parameter k ($k=-2.21, -1.41, 2.31$ and 4). And in LFCCs parameterization, the feature vectors dimensionality is the same as MFCC vectors. Hence, we have conducted verification tests with added noises (Babble-speech and factory) extracted from the database Noisex-92 (NATO: AC 243/RSG 10) at different level of SNR (0, 5, 10 and 15 dB).

4 EXPERIMENTAL RESULTS

4.1 Speaker Verification in Quite Environment

In this section, we compare the performance of MFCCs, LFCCs and Asymmetric taper MFCC in term of EER in clean environment ($SNR \geq 40$ dB).

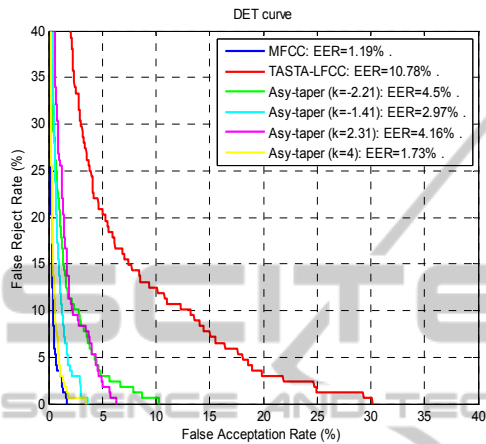


Figure 3: DET curves.

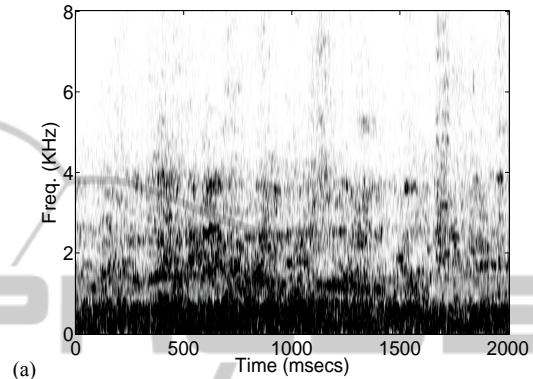
As shown in Figure 3, we find that, MFCC (EER=1.19%) and MFCC based on asymmetric tapers (EER=1.73%) outperform RAST-LFCC (EER=10.78%). This can be caused by the fact that LFCCs have more filterbanks in high frequency region, which differs from the mechanism of perception of the human ear at this region.

4.2 Speaker Verification in Noisy Environment

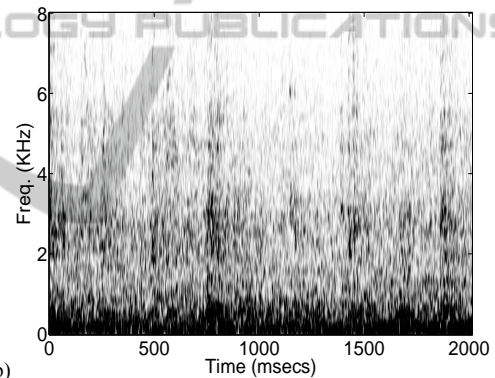
To test the performances of all feature methods with real noise, we used some of the noise samples babble-speech and factory extracted from the NOISEX-92 database shown by Figure 4. These noises were added to test speech data after being scaled.

From the Table 1, it is observed that, despite a drops accuracy of all methods as SNR decreases, we find that asymmetric tapers appear robust in noisy conditions than other features extraction methods. Also, it is observed from the same table that the asymmetric tapers performed better than the symmetric Hamming taper in the most of the noisy conditions (babble and factory) in term of ERR. Compared to the baseline Hamming taper, asymwind with $k=4$ provides an improvement in term of EER of 30.35%, 14.88% under babble noise at $SNR = 0$ dB, 5 dB, 40.72%, 32.73 % under factory

noise at $SNR = 0$ dB, 5 dB. In LFCC method, the spectrum energy in the high frequency region of speech is weak and it is more susceptible to noise corruption. As Linear Frequency Cepstral Coefficients has more filterbanks in this region (high frequency), so it is less robust in the noises that characterized by high frequency than MFCC and asymmetric tapers in term of EER.



(a)



(b)

Figure 4: Spectrograms of a) Babble noise, b) Factory noise.

4.3 Score Fusion

A further step toward improving of the performance of speaker verification system is investigating a possible complementarily between different features. For this aim, several techniques of fusion (simple sum, max, min and SVM bi-class based on RBF kernel) have been applied to the scores of different systems using different parameters. Also, in order to evaluate the performance of our scores fusion approaches in terms of EER, we calculated the relative improvement between EER of each method of scores fusion and best EER given by best taper in Table 1.

$$RI = \frac{EER_{\text{fusion}} - EER_{\text{best-taper}}}{EER_{\text{best-taper}}} \times 100 \quad (5)$$

Table 1: Equal Error Rate (EER%) of all methods under noisy environment.

Features		Baseline (MFCC)	RASTA-LFCC	MFCC-ASY K=-1.41	MFCC-ASY K=-2.21	MFCC-ASY K=2.31	MFCC-ASY K=4
Babble	15	8.16	23.44	6.10	3.81	4.59	2.38
	10	18.09	28.92	13.81	8.29	10.98	5.96
	5	25.52	33.70	25.28	21.71	22.62	14.88
	0	34.20	39.01	35.76	32.90	33.37	30.35
Factory	15	12.89	19.46	9.59	10.47	9.71	7.14
	10	23.49	24.28	24.28	23.21	22.77	18.45
	5	35.36	35.16	37.41	35.60	35.71	32.73
	0	44.70	42.33	44.48	43.65	42.26	40.72

Table 2: Equal Error Rate (EER) of sum fusion.

Noise SNR	Babble		Factory	
	EER(%)	RI(%)	EER(%)	RI(%)
0	30.37	0.07	37.70	-7.42
5	19.64	31.99	28.21	-13.81
10	7.74	29.87	13.79	-28.51
15	1.86	-21.85	5.52	-22.69

Table 3: Equal Error Rate (EER) of min fusion.

Noise SNR	Babble		Factory	
	EER(%)	RI(%)	EER(%)	RI(%)
0	34.84	14.79	34.86	-14.39
5	26.58	78.63	29.76	-9.07
10	16.83	82.38	19.80	7.32
15	8.92	74.79	11.90	66.67

Table 4: Equal Error Rate (EER) of max fusion.

Noise SNR	Babble		Factory	
	EER(%)	RI(%)	EER(%)	RI(%)
0	31.54	3.62	44.64	9.63
5	17.44	17.20	37.50	14.57
10	5.38	-9.73	13.76	-25.42
15	2.38	0	8.40	17.65

Table 5: Equal Error Rate (EER) of svm fusion.

Noise SNR	Babble		Factory	
	EER(%)	RI(%)	EER(%)	RI(%)
0	19.04	-37.27	24.40	-40.08
5	13.08	-12.10	19.64	-39.99
10	7.74	29.87	18.34	-0.60
15	2.97	24.79	11.31	58.40

As shown in Table 1, 2, 3 and 4 there is an improvement in terms of ERR when a scores fusion is applied to the different feature vectors (MFCCs, RASTA-LFCCs and asymmetric MFCCs), this validates our assumption about the complimentary existing between these parameters. Also it is observed that, at level SNR = 10 dB and 15 dB, the simples methods (for example fusion with sum: Babble noise: EER = 7.74% at 10dB and EER =

1.86% at 15 dB. Factory noise: EER = 13.79% at 10dB and EER = 5.52% at 15 dB) provide better results compared to SVM. By cons, in situations where the environment is very noisy (SNR = 0 dB and 5 dB), we see that, the SVM provides a significant improvement in term of ERR (Babble noise: EER = 19.04% at 0dB and EER = 13.08% at 5 dB. Factory noise: EER = 24.40% at 0dB and EER = 19.64% at 5 dB). This can be explained by the fact that in low-noisy environments (SNR >= 10dB), the scores issued from different classifiers are linearly separable therefore a simple linear fusion can do the trick (good results). By cons, when environment becomes very noisy (SNR < 10 dB), data (scores) become non-linearly separable (overlapping data), so here SVM appears better than simple methods.

5 CONCLUSIONS

In this paper, different feature extraction methods were studied for speaker verification system based on GMM-UBM classifier in clean and noisy conditions. MFCC outperformed LFCC and MFCC based on asymmetric tapers in calm conditions. However, under two different additive noise types, factory and babble noises, MFCC based on asymmetric tapers (k=4) gave the best performances than other. When a fusion score have applied on our features, we observed that this fusion brings an important amelioration in performance of GMM-UBM model. The focus of our work, was to find the features which provide a good speaker verification performances in term of equal error rate, especially under real world in goal to use them in our future works.

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